Development of a holistic approach for force and strain measurements in high-speed tensile tests

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Introduction

Crash loads with high strain rates can often be found in automotive and aerospace industries, so that a material characterization on dynamic basis is required to guarantee safety properties of highly loaded components. Most exterior parts nowadays are made of fiber-reinforced polymers (FRP), which show strain rate dependent properties [1-3]. For this purpose, the determination of characteristic parameters in high-speed tensile tests is a common method. Since FRP show an increasing ultimate tensile strength (σ_{UTS}) with higher strain rates, a high potential regarding material savings and lightweight design is enabled. Consequently, a comprehensive understanding of the data, which is measured in high-speed tensile tests, is necessary. Typically, the test force is provided by a piezo-electric load cell, whereas the piston movement is recorded by a capacitive sensor. This is also how it is realized with the high-speed impact testing machine HITS-TX, Figure 1. Furthermore, HITS-TX provides an additional grip displacement sensor (GDS) for measuring the specimen movement just inside the grips and therefore excluding influences of additional parts in the load train. This is in accordance with existing knowledge about oscillations and stress waves in load train, influencing recorded force and displacement signals. [4,5]

A general challenge of high-speed material testing is the impact occurring between the approach jig and actuator piston at test beginning. An approach device is usually used in high-speed systems in order to accelerate the piston to the desired test speed, before the specimen is loaded. As a result of the impact inside this device, oscillations, which are travelling as elastic stress waves, are transmitted to the load train. These waves are reflected in the load cell at the bottom of the test system and, as a consequence, influencing force and displacement measurements. In order to avoid or at least to reduce these oscillations, it is essential to install a mechanism for damping the force application. For this purpose, different materials or geometries at the contact surfaces can be used, as well as installing damping elements. However, the effect of damping should no longer have an influence on the measurement at a load of 25% of the yield strength [5].

Materials and methods

For investigations, a composite material made of glass fiber-reinforced epoxy (GFR-EP) is used, as a good representation of the material group mentioned above. The material is reinforced with bidirectional glass fibers in 0/90° orientations. Based on several studies, a positive strain rate dependency is expected [1-3]. The specimen geometry, Figure 2, is a further development of the specimen geometry and was specially adapted to the measurement with a high-speed video camera. In detail, the specimen provides an additional dynamometer section to enable force calculation with the help of digital image correlation (DIC).
The test setup (Figure 3) consists of a HITS-TX system with a piston stroke sensor, connected to a 4870 type controller, along with an additional grip displacement sensor (GDS), as well as a hyper vision high-speed video camera (HPV-X2, Figure 4). In addition, the HITS-TX system provides various approach jigs in order to optimally adapt the geometry and damping effects to the selected test speed. On the one hand, there is a tapered version with two lengths available. On the other hand, a flat version of the approach jig can be used. While the flat version is equipped with a shock-absorbing rubber, the tapered versions are using the contact surface to absorb test forces, as well as a combination of two rubber rings to prevent multiple collisions. In summary, the flat version should be used up to 8 m/s, while the tapered version is then used up to 20 m/s (72 km/h). In this work, high-speed tensile tests at 5, 6.5, 8 and 12 m/s in combination with the flat and tapered version of the approach jig are carried out. According to [6], the speeds are corresponding to nominal strain rates of 920, 1,200, 1,480, and 2,220 s\(^{-1}\). In order to achieve highest recording rates with the HPV-X2 camera, an exposure time as short as possible is needed. Consequently, three light sources are installed, one high-power LED with 15,000 lumen just below the lens and two HMI-lights with each 400 W placed on either side. Another challenge that comes with high-speed imaging, is the triggering of the camera [7]. For this purpose, the 4870 type controller of the HITS-TX system provides a TTL 5 V signal, while timing is controlled via piston stroke. With the help of a synchronization signal from HPV-X2 camera to HITS-TX system, reproducible results could be achieved.

Since the HPV-X2 camera has a limited ring buffer, the number of images recorded at full resolution is limited to 128. However, it is possible to set the number of images to 256 when using a special interpolation, which leads to a smaller overall resolution. Therefore, it is mandatory to know the exact test time and to set the recording rate accordingly. In this case, the test times observed are between 100 and 200 μs, depending on the test speed. Test times of 200 μs are corresponding to a maximum theoretical recording rate of 640,000 frames per second (fps), provided that the trigger point in time is set perfectly. To compensate for deviations in timing, the actual recording rate is set to 250,000 fps.
• **Results and discussion**

In order to determine material properties in high-speed tests in general, different strain measurement techniques, such as strain gages, optical extensometers, laser systems or high-speed cameras, can be used [6]. By additional DIC-analysis of high-speed images the visualization of strain distribution on the entire specimen becomes available. The same applies to force measurements, which can either be done by system-integrated load cells or inertia-free techniques.

**a. Force measurement**

In order to assess the quality of the force measurement with a load cell, a comparison to forces calculated by DIC-analysis and HPV-X2 camera is done. A precise measurement is becoming available, when designing a dynamometer section for the specimen. Therefore, a slightly asymmetrical specimen is used for these investigations (Figure 5). This geometry allows a strain measurement in the gage section and a force measurement in the dynamometer section with DIC-analysis at the same time.

Normally, the dynamometer section is an area, where no plastic deformation occurs. Transferred for FRP’s a section is meant, where the determination of Young’s modulus is allowed. Since the determination of Young’s modulus is allowed within the limits of 0.05 to 0.25% [8], a varying modulus versus the total strain is implemented, which is suitable for the visco-elastic material behavior of GFR-EP. Thus, the force, which is actually appearing on the specimen, can be determined by $\sigma = E \cdot \varepsilon$ (Hooke’s Law) $\Rightarrow F = E \cdot \varepsilon \cdot A$.

However, the Young’s modulus has to be determined on a dynamic basis, because quasi-static material properties cannot be transferred to high-speed testing. Thus, the only possibility to determine a correct Young’s modulus is then a calculation within the short period of time in between of the impact at the approach jig and the elastic stress waves travelling until reaching the load cell at the bottom of the test system. Furthermore, it is important to average the measured strain in the dynamometer section over the same specimen width, which the cross section A is related to.

**Figure 5** shows the comparison of test forces measured by load cell versus DIC, when using a tapered approach jig and a test speed of 8 m/s. The varying modulus mentioned above is related to the course of the mean strain (blue box) of 0 to 0.8% throughout the entire test.

**b. Displacement and strain measurement**

With the presented test setup, there are several techniques for strain measurement available: Piston stroke, GDS, and DIC. While the piston stroke is measuring the actual piston movement at the top of the load train, the GDS is just measuring the displacement between the grips. With DIC-analysis, on the other hand, displacements and strains can be recorded directly at the specimen.
Thus, only with DIC-analysis it is possible to determine true strains. Differences between these methods are expected, which could be due to the following influences:

- Components with different rigidities involved in the load train
- Elastic deformation of components in the load train
- Dampening effects by compression and force-absorbing properties of the rubber
- Measuring distance to the specimen.

As can be seen in Figure 6, the effects mentioned above could lead to significant deviations in the resulting strain curves. As expected, the piston stroke sensor is quite linear and differs greatly from the other curves, since most components and their deformation are included in this measurement. Furthermore, the impact and multiple collisions with the approach jig could be recorded by piston stroke. The deviations between GDS and DIC is small at low strains, but the increases as the test time progresses. But, as can be seen in the enlarged section, the slopes of the applied tangents within the given limits are equaling, thus the GDS is working well within small strains, where effects like specimen bending, clamping issues or clearance come into account.

In order to visualize the strain distribution at the specimen, Figure 7 shows the total strain at different test times. It is obvious, that the specimen geometry is working well, since the strain distribution in the gage section is homogenous. However, an inhomogeneous strain distribution can be seen in the dynamometer section, which is due to the bidirectional fiber orientation. Since the specimen is made of continuous fibers, the load in 0°-layers in the middle of the specimen is being transferred from gauge to dynamometer section, whereas the outer fibers are subjected to a smaller force. From these findings it can be concluded that every local strain measurement, like strain gages, will not work properly for measuring force in the dynamometer section, since an inhomogeneous strain distribution can be found there.

**Figure 7:** Specimen strain distribution at diff. test times

- **Conclusions and outlook**

Within this work at high-speed impact testing machine HITS-TX, a comparison of system integrated and additional techniques for measuring test forces and displacements was conducted. Especially these two parameters were defined as critical, since they can be influenced by oscillations, which are consequences of the impact inside the approach device. An innovative measurement with the help of HPV-X2 camera and DIC-analysis is presented, with which true test forces and total strains can be calculated.

It could be shown that the force signal of the load cell shows only slight deviations from DIC-analysis, so that generating material properties is made possible especially with low strains, as in...
modulus determination. This procedure can be used for applications like creating material data for simulation purposes, especially if component testing in high-speed or crash load regime is cost-intensive.

Regarding displacement and strain measurements, a clear dependency on the use of the appropriate measuring technique was pointed out. Where GDS can be used at low strains, it is essential to use DIC-analysis when determining total strains at the specimen failure. With the help of DIC, a local strain measurement and a strain distribution on the entire specimen could also be realized. Due to the triggering and synchronization by connecting HPV-X2 and HITS-TX, a sufficient number of images for strain evaluation is always ensured as well as a comfortable data analysis.

### References

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